

# Self-contracted curves in Riemannian manifolds

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**Abstract** It is established that every self-contracted curve in a Riemannian manifold has finite length, provided its image is contained in a compact set.

**Key words** Self-contracted curve, self-expanded curve, rectifiable curve, length, secant, Riemannian manifold.

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## 1. INTRODUCTION

This work is devoted to the study of self-contracted curves.

**Definition 1.1** (Self-contracted curve). Given an interval  $I = [0, T_\infty)$  with  $T_\infty \in [0, \infty) \cup \{\infty\}$ , a curve  $\gamma : I \rightarrow \mathcal{M}$  is called *self-contracted*, if for every  $t_1 \leq t_2 \leq t_3$  in  $I$  we have

$$d_g(\gamma(t_1), \gamma(t_3)) \geq d_g(\gamma(t_2), \gamma(t_3)). \quad (1.1)$$

In other words, for every  $\tau \in [0, T_\infty)$  the function  $t \mapsto d_g(\gamma(t), \gamma(\tau))$  is nonincreasing on  $[0, \tau]$ .

Self-contracted curves were introduced in [3, Definition 1.2.]. The motivation of this definition comes from the following example.

**Example 1.2.** If  $f : \mathbb{R}^n \rightarrow \mathbb{R}^+$  is a  $\mathcal{C}^1$ -smooth convex function and if  $\gamma : (0, +\infty) \rightarrow \mathbb{R}^n$  is smooth and satisfies  $\gamma'(t) = -\nabla f(\gamma(t))$  for all  $t > 0$ , then  $\gamma$  is a self-contracted curve.

Indeed, observe first that  $(f(\gamma(t)))' = -\|\nabla f(\gamma(t))\|^2 \leq 0$ , thus the function  $t \mapsto f(\gamma(t))$  is nonincreasing. Therefore, since  $f$  is convex, if  $\tau \geq t$ , then

$$\frac{d}{dt} \left( \frac{1}{2} \|\gamma(\tau) - \gamma(t)\|^2 \right) = \langle \gamma(\tau) - \gamma(t), \nabla f(\gamma(t)) \rangle \leq f(\gamma(\tau)) - f(\gamma(t)) \leq 0.$$

This proves that the function  $t \mapsto \|\gamma(t) - \gamma(\tau)\|$  is nonincreasing on  $[0, \tau]$ .

One of the main interests in studying self-contracted curves lies in its applications. Rectifiability of self-contracted curves has been applied in different areas, including continuous and discrete dynamical systems, optimization and convergence of algorithms. See for example [3] and [4].

The definition of self-contractedness is purely metric: if  $\varphi$  is a nondecreasing function from an interval  $J$  onto  $I$ , then  $\gamma \circ \varphi$  is also self-contracted, so this notion does not depend on the particular parametrization of the oriented graph  $\{\gamma(t); t \in I\}$ . Self-contractedness does not require prior smoothness or continuity assumption on the curve as shown by the following example.

**Example 1.3.** Let  $\gamma : \mathbb{R} \rightarrow \mathbb{C}$  defined by  $\gamma(t) = t$  if  $t \leq -1$ ,  $\gamma(t) = -t$  if  $-1 < t \leq 0$  and  $\gamma(t) = it$  if  $t > 0$ . The curve  $\gamma$  is self-contracted, is not smooth at  $t = 0$ , is discontinuous at  $t = -1$ , and moreover does not admit a continuous self-contracted extension, *i.e.* there exists no continuous self-contracted curve  $\Gamma : \mathbb{R} \rightarrow \mathbb{C}$  such that  $\{\Gamma(t) : t \in \mathbb{R}\} \supset \{\gamma(t) : t \in \mathbb{R}\}$ .

In a Euclidean setting it has been established in [4, Section 3] (and independently in [8] for continuous curves) that bounded self-contracted curves have finite length. In both cases the proof was based on an old result of Manselli-Pucci [10] which allows to deduce that all self-contracted curves lying in a given ball have lengths which are uniformly bounded. Applications of this fact have been discussed in [4, Section 4], [2].

The results of [10], [3], [4], [8] are all heavily based on the Euclidean structure. In [7] the author establishes rectifiability for planar curves in the non-Euclidean case, while in [5] the authors consider (under a different terminology) absolutely continuous self-contracted curves in a bounded convex subset of a two-dimensional complete surface of constant Gaussian curvature, and provide an upper bound for the length, but in case of a surface of positive curvature (sphere), they made the additional assumption that the diameter of this subset was strictly less than  $\pi/2$ .

In this work we establish that any self-contracted curve in a compact set of a smooth Riemannian manifold has finite length. This result generalizes the results mentioned above. In particular, contrary to [5] it does not require any assumption on the curvature or on the dimension of the manifold. Moreover, our result holds in the case of discontinuous self-contracted curves.

## 2. MAIN RESULT

**2.1. Statement of the main result.** Let  $(\mathcal{M}, g)$  be a smooth complete Riemannian manifold whose geodesic distance is denoted by  $d_g$ . Given an interval  $I = [0, T_\infty)$  with  $T_\infty \in [0, \infty) \cup \{\infty\}$ , the *length* of a curve  $\gamma : I \rightarrow \mathcal{M}$  is defined as

$$\ell(\gamma) := \sup \left\{ \sum_{i=0}^{m-1} d_g(\gamma(t_i), \gamma(t_{i+1})) \right\}, \quad (2.1)$$

where the supremum is taken over all finite increasing sequences  $t_0 < t_1 < \dots < t_m$  that lie in the interval  $I$ . We say that a (possibly discontinuous) curve  $\gamma : I \rightarrow \mathcal{M}$  has *finite length* if  $\ell(\gamma)$  is finite. Any continuous curve  $\gamma : I \rightarrow \mathcal{M}$  with finite length can be reparameterized into a Lipschitz curve on  $[0, \ell(\gamma)]$  with speed of constant norm *a.e.* equal to 1. The following extends previous results by [5], [4], [8].

**Theorem 2.1** (Main result). *Let  $(\mathcal{M}, g)$  be a smooth Riemannian manifold,  $\mathcal{K}$  be a compact subset of  $\mathcal{M}$  and  $\gamma : I \rightarrow \mathcal{K}$  be a self-contracted curve. Then  $\gamma$  has finite length.*

This result does not extend in an infinite dimensional setting.

**Example 2.2.** Let  $\gamma : [1, +\infty) \rightarrow L^2(\mathbb{R})$  given by  $\gamma(t)(s) = \frac{1}{\sqrt{s}}$  if  $s \in (t, t+1)$  and 0 otherwise. It is easy to see that  $\gamma$  is a self-contracted curve, its closure is equal to  $\{\gamma(t); t \in [1, +\infty)\} \cup \{0\}$  (therefore it is compact in  $L^2(\mathbb{R})$ ) and its length is infinite (indeed, since  $\|\gamma(n+1) - \gamma(n)\|_2 = \sqrt{\ln(1+2/n)} \geq 1/n$ , the series  $(\sum \|\gamma(n+1) - \gamma(n)\|_2)$  diverges).

The rest of the paper is devoted to the proof of Theorem 2.1.

**2.2. Notation and sketch of the proof.** The symbol  $\mathcal{M}$  will always stand for a smooth manifold of dimension  $n \geq 2$  whose tangent bundle is denoted by  $T\mathcal{M}$ . Elements of  $T\mathcal{M}$  are denoted by  $\xi = q_y = (y, q)$  with  $q \in T_y\mathcal{M}$ . Given a smooth Riemannian metric  $g$ , we denote the metric at  $x \in \mathcal{M}$  by  $\langle \cdot, \cdot \rangle_x$  and its norm by  $|\cdot|_x$ . We sometimes omit  $x$  if no ambiguity arises. The geodesic distance is denoted by  $d_g$  and the open geodesic ball centered at  $x$  of radius  $r \geq 0$  is denoted by  $B_g(x, r)$ . For every  $x \in \mathcal{M}$ , we denote by  $\exp_x : T_x\mathcal{M} \rightarrow \mathcal{M}$  the exponential mapping at  $x$ . We denote by  $\widehat{B}_x$  the balls in  $T_x\mathcal{M}$  (with respect to the Euclidean metric in  $T_x\mathcal{M}$ ). We denote the unit tangent bundle associated with  $g$  by  $U\mathcal{M}$ , that is,

$$U\mathcal{M} := \{u_x \in T\mathcal{M} : |u|_x = 1\}.$$

If  $\mathcal{K}$  is a compact subset of  $\mathcal{M}$ , then

$$UK := \{u_x \in T\mathcal{M} : x \in \mathcal{K} \text{ and } |u|_x = 1\}$$

is a compact subset of  $U\mathcal{M}$ . We consider a canonical Riemannian metric on the unit bundle, whose associated distance is denoted by  $D_g$ . We may assume that for every  $p_x, q_y$  in  $U\mathcal{M}$  it holds

$$D_g(p_x, q_y) \geq d_g(x, y). \quad (2.2)$$

We refer to [1], [6] for prerequisites on Riemannian manifolds.

We now present the strategy of proof of the main theorem. Every self-contracted curve has left limit and right limit at each point. We show that if such a curve is contained in a compact subset of  $\mathcal{M}$ , then the set of points of large discontinuities (*i.e.* the set of points where the oscillation of  $\gamma$  is greater than some fixed threshold  $\eta > 0$ ) is finite and its cardinal depends only on  $\mathcal{K}$ . Then we do a detailed study of the local behaviour of the curve around points of continuity and/or points of small discontinuity. The main tool here is a uniform cosine law for small triangles having one vertex in the compact  $\mathcal{K}$ . This study allows us to construct an element  $p^a \in U\mathcal{M}$ , called almost secant, such that the curve  $\gamma$  grows in this direction around the point  $x = \gamma(\tau)$ . Finally, we consider an  $\eta$ -net  $\mathcal{F}$  of  $UK$ . For  $\xi := q_y \in \mathcal{F}$  and for  $z \in \mathcal{M}$  such that  $d_g(z, y)$  is sufficiently small, we define the local width of  $\gamma$  at  $x = \gamma(\tau)$  with respect to  $q_y$  by  $W_\xi(\tau) := \text{diam} \{ \langle q, \exp_y^{-1}(\gamma(t)) \rangle_y : t \geq \tau, \gamma(t) \in B_g(y, 2\eta) \}$ . Notice that  $\tau \mapsto W_\xi(\tau)$  is a nonincreasing (Lyapunov) function. We deduce from the study of the local behaviour of  $\gamma$ , that if  $\tau$  is not a point of large discontinuity and if  $s, t$  are in a neighborhood of  $\tau$  and  $s \leq \tau \leq t$ , then at least one of the Lyapunov functions  $W_\xi$  ( $\xi \in \mathcal{F}$ ) satisfies  $W_\xi(s) - W_\xi(t) \geq \alpha d_g(\gamma(s), \gamma(t))$ , where

$$\alpha = \frac{1}{32(n+1)^2} \quad (n = \dim \mathcal{M}). \quad (2.3)$$

Since the curve  $\gamma$  is contained in the compact set  $\mathcal{K}$ , all functions  $W_\xi$  are bounded. This together with the above inequality, implies the rectifiability of  $\gamma$ .

**2.3. Exponential map - Cosine law - External functions.** We introduce here a few tools from Riemannian manifolds. We first notice that for every  $x \in \mathcal{M}$ , there exists  $r > 0$ , such that the exponential function  $\exp_x$  is a smooth diffeomorphism between the open ball  $\widehat{B}_x(0, r)$  of  $T_x\mathcal{M}$  onto the open geodesic ball  $B_g(x, r)$  in  $\mathcal{M}$ . The following lemma is an easy consequence of the compactness of  $\mathcal{K}$  and the smoothness of the geodesic flow.

**Lemma 2.3.** *There exists  $\rho > 0$  such that for every  $x \in \mathcal{K}$ ,  $\exp_x$  is a smooth diffeomorphism from the ball  $\widehat{B}_x(0, 2\rho)$  to its image  $B_g(x, 2\rho)$ .*

Thus, we can define, for any  $x \in \mathcal{K}$  and  $z \in B_g(x, \rho)$ ,

$$u_x(z) := \frac{\exp_x^{-1}(z)}{|\exp_x^{-1}(z)|_x} \in U_x\mathcal{M} \quad (\text{provided } z \neq x). \quad (2.4)$$

By construction,  $\exp_x^{-1}(z)$  is the initial velocity of the geodesic  $\theta : [0, 1] \rightarrow \mathcal{M}$  joining  $x$  to  $z$ , so we have  $|\exp_x^{-1}(z)|_x = d_g(x, z)$ .

Recall that if  $x, y, z$  lie in a Euclidean space, the law of cosines asserts that

$$\|y - z\|^2 = \|y - x\|^2 + \|z - x\|^2 - 2\langle y - x, z - x \rangle$$

The following result asserts that small geodesic triangles in a Riemannian manifold almost satisfy the law of cosines, see FIG. 1 for an illustration.

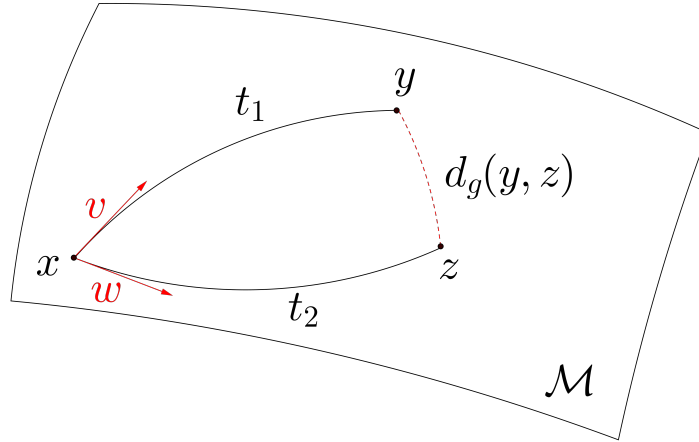


FIGURE 1. Cosine law in Riemannian manifolds.

**Lemma 2.4** (Cosine law in manifolds). *There exists  $K > 0$  such that for every  $x \in \mathcal{K}$  and every  $y, z \in B(x, \rho)$ ,*

$$|d_g^2(y, z) - d_g^2(x, y) - d_g^2(x, z) + 2\langle \exp_x^{-1}(y), \exp_x^{-1}(z) \rangle_x| \leq K d_g(x, y)^2 d_g(x, z)^2 \quad (2.5)$$

**Proof.** By Lemma 2.3, there exist  $t_1, t_2 \in (-\rho, \rho)$ ,  $v, w \in U_x\mathcal{M}$  such that  $y = \exp_x(t_1 v)$  and  $z = \exp_x(t_2 w)$ , precisely  $t_1 = d_g(x, y) = |\exp_x^{-1}(y)|_x$  and  $t_2 = d_g(x, z) = |\exp_x^{-1}(z)|_x$ . For fixed  $x \in \mathcal{K}$  and  $v, w \in U_x\mathcal{M}$ , we consider the function  $\Phi : (-\rho, \rho)^2 \rightarrow \mathbb{R}$  defined by

$$\Phi(t_1, t_2) = d_g(\exp_x(t_1 v), \exp_x(t_2 w))^2$$

We check easily that for every  $t_1, t_2 \in (-\rho, \rho)$ ,

$$\Phi(t_1, 0) = t_1^2, \quad \Phi(0, t_2) = t_2^2,$$

and

$$\frac{\partial \Phi}{\partial t_1}(0, t_2) = -2 t_2 \langle v, w \rangle_x, \quad \frac{\partial \Phi}{\partial t_2}(t_1, 0) = -2 t_1 \langle v, w \rangle_x.$$

Then we infer that

$$\frac{\partial^2 \Phi}{\partial t_1 \partial t_2}(0, 0) = -2 \langle v, w \rangle_x$$

and for every integer  $k \in \{2, 3\}$ ,

$$\frac{\partial^{k+1} \Phi}{\partial t_1^k \partial t_2}(0, 0) = \frac{\partial^{k+1} \Phi}{\partial t_1 \partial t_2^k}(0, 0) = 0.$$

The Taylor expansion formula of order 4 for the function  $\Phi$  shows that there exists  $K > 0$  (depending on the fourth derivative of the exponential mapping at  $x$ ) such that

$$|\Phi(t_1, t_2) - t_1^2 - t_2^2 + 2 t_1 t_2 \langle v, w \rangle_x| \leq K t_1^2 t_2^2, \quad \forall t_1, t_2 \in (-\rho, \rho).$$

By the definition of the exponential map, we have  $\Phi(t_1, t_2) = d_g(y, z)^2$ ,  $t_1 = d_g(x, y)$ ,  $t_2 = d_g(x, z)$ ,  $t_1 v = \exp_x^{-1}(y)$  and  $t_2 w = \exp_x^{-1}(z)$  so the above formula implies equation (2.5). The compactness of  $UK$  shows that the constant  $K$  can be chosen independently of  $x, v, w$ .  $\square$

**Remark 2.5** (Adapting the constant  $\rho$ ). Let  $K > 0$  be given by Lemma 2.4. We may always shrink  $\rho > 0$  of Lemma 2.3 to ensure

$$4K \rho^2 \leq \alpha. \quad (2.6)$$

In the following result, we introduce a parameter  $\eta$  that will be fixed throughout the paper, and we give a control of the difference of the growths of the mappings  $z \rightarrow \langle p, \exp_x^{-1}(z) \rangle_x$  and  $z \rightarrow \langle q, \exp_y^{-1}(z) \rangle_y$  around  $x$  whenever  $D_g(p_x, q_y) < \eta$ .

**Lemma 2.6.** *Let  $\alpha > 0$  be given by (2.3). Then there exists  $\eta \in (0, \rho/4)$  such that for every  $p_x \in UK$ ,  $q_y \in B_{D_g}(p_x, \eta)$  (Riemannian ball in the unit bundle  $U\mathcal{M}$ ), and  $z \in B_g(y, 2\eta)$  we have*

$$|\langle q, \exp_y^{-1}(z) \rangle_y - \langle q, \exp_y^{-1}(x) \rangle_y - \langle p, \exp_x^{-1}(z) \rangle_x| \leq \alpha d_g(x, z).$$

**Proof.** Let us denote  $b_{p_x}(z) := \langle p, \exp_x^{-1}(z) \rangle_x$  and  $b_{q_y}(z) := \langle q, \exp_y^{-1}(z) \rangle_y$ . We first claim that for every  $p_x$  in  $UK$ ,

$$\nabla b_{p_x}(x) = p \in T_x \mathcal{M}.$$

Since the differential  $D \exp_x^{-1}(x)$  is the identity mapping on  $T_x \mathcal{M}$  it follows by the chain rule that  $D b_{p_x}(x) = \langle p, \cdot \rangle_x$ . This proves the claim. Since the mapping

$$(q_y, x) \mapsto D b_{q_y}(x) = \langle q, D \exp_y^{-1}(x)(\cdot) \rangle_y$$

is continuous, we deduce easily from the compactness of  $\mathcal{K}$  and  $UK$  and the claim that there exists  $\eta > 0$  such that for all  $p_x, q_y$  in  $UK$  satisfying  $D_g(p_x, q_y) < \eta$  we have

$$|\nabla b_{q_y}(x) - \nabla b_{p_x}(x)|_x = |\nabla b_{q_y}(x) - p|_x < \frac{\alpha}{2}. \quad (2.7)$$

We claim now that there exists  $L > 0$  such that for every  $q_y \in UK$  and  $x, z \in B_g(y, \rho)$  it holds (recall notation (2.4)) :

$$|b_{q_y}(z) - b_{q_y}(x) - \langle \nabla b_{q_y}(x), \exp_x^{-1}(z) \rangle_x| \leq L |\exp_x^{-1}(z)|_x^2.$$

Indeed, the mapping

$$(q_y, x) \mapsto b_{q_y}(x) := \langle q, \exp_y^{-1}(x) \rangle_y$$

is smooth (whenever it is well-defined, that is,  $d_g(x, y) \leq 2\rho$ ). The exact Taylor expansion of order 2 for the function  $z \mapsto b_{q_y}(z)$  at the point  $x$ , together with the compactness of  $\mathcal{K}$  and  $UK$  and a standard argument gives the above inequality. We now shrink  $\eta > 0$  if necessary to ensure that  $\eta \leq \alpha/6L$ . Pick any  $z \in B_g(y, 2\eta) \subset B_g(y, \rho)$ . It follows from (2.2) that if  $D_g(p_x, q_y) < \eta$ , then  $d_g(x, y) < \eta$ , and so  $d_g(x, z) < 3\eta$ . Since  $|\exp_x^{-1}(z)|_x = d_g(x, z) < 3\eta \leq \alpha/2L$  the above inequality becomes

$$|b_{q_y}(z) - b_{q_y}(x) - \langle \nabla b_{q_y}(x), \exp_x^{-1}(z) \rangle_x| \leq \frac{\alpha}{2} d_g(x, z). \quad (2.8)$$

Equation (2.7) implies  $|\langle \nabla b_{q_y}(x) - p, \exp_x^{-1}(z) \rangle_x| \leq \alpha/2 d_g(x, z)$ . This inequality combined with (2.8) yields the inequality of Lemma 2.6.  $\square$

### 3. GEOMETRICAL DESCRIPTION OF SELF-CONTRACTED MAPS

**3.1. Dealing with discontinuities.** Let  $\gamma : I \rightarrow \mathcal{M}$  be a self-contracted curve such that  $\gamma(I) \subset \mathcal{K}$  with  $\mathcal{K}$  compact. The results of this sub-section are valid assuming only that  $\mathcal{M}$  is a metric space. For every  $\tau \in I$ , we denote by  $\gamma(\tau^-)$  the left limit of  $\gamma$  at  $\tau$ , that is,

$$\gamma(\tau^-) := \lim_{s < \tau, s \rightarrow \tau} \gamma(s),$$

**Proposition 3.1.** *The above limit always exists.*

**Proof.** Otherwise, by compactness, there would exist at least two accumulation points  $x_1$  and  $x_2$  with  $l = d(x_1, x_2) > 0$ . Let  $t_1 < t_2 < t_3 < \tau$  be such that  $d(\gamma(t_1), x_1) < l/4$ ,  $d(\gamma(t_2), x_2) < l/4$  and  $d(\gamma(t_3), x_1) < l/4$ . Since  $\gamma$  is self-contracted, we have

$$l/2 > d(\gamma(t_1), \gamma(t_3)) \geq d(\gamma(t_2), \gamma(t_3)) > l/2$$

which is a contradiction.  $\square$

We denote by  $\mathcal{D}^- := \{\tau \in I : \gamma(\tau) \neq \gamma(\tau^-)\}$  the set of points where  $\gamma$  is not left continuous. We fix  $\eta > 0$  satisfying Lemma 2.6, and we set:

$$\text{(left-}\eta\text{-threshold)} \quad \mathcal{D}^-(\eta) := \{\tau \in I : d_g(\gamma(\tau), \gamma(\tau^-)) \geq \eta\}. \quad (3.1)$$

In the following lemma, the cardinality of a set  $S$  is denoted by  $|S|$ .

**Proposition 3.2** (Cardinality of  $\mathcal{D}^-(\eta)$ ). *Let  $\gamma : I \rightarrow \mathcal{M}$  be a self-contracted map such that  $\gamma(I) \subset \mathcal{K}$ . If  $N(\eta)$  is the minimal number of balls of radius  $\eta/2$  that can cover  $\mathcal{K}$ , we have*

$$|\mathcal{D}^-(\eta)| = |\gamma(\mathcal{D}^-(\eta))| \leq N(\eta). \quad (3.2)$$

In particular, since  $\mathcal{D}^- = \bigcup_{n \in \mathbb{N}} \mathcal{D}^-(1/n)$ ,  $\mathcal{D}^-$  is at most countable.

**Proof.** We first claim that for any  $x \in \mathcal{M}$  we have :

$$|\gamma(\mathcal{D}^-(\eta)) \cap B_g(x, \eta/2)| \leq 1.$$

Let  $\tau_1, \tau_2 \in \mathcal{D}^-(\eta)$  with  $\tau_1 < \tau_2$ , be such that  $\{\gamma(\tau_1), \gamma(\tau_2)\} \subset B_g(x, \eta/2)$ . Set  $x_i = \gamma(\tau_i)$  and  $x'_i = \gamma(\tau_i^-)$ ,  $i \in \{1, 2\}$ . It follows that  $\{x_1, x_2\} \subset B_g(x, \eta/2)$  and  $\{x'_1, x'_2\} \subset \mathcal{M} \setminus B_g(x, \eta/2)$ . The fact that  $\gamma$  is self-contracted yields the following inequalities:

$$\eta \leq d_g(x'_2, x_2) \leq d_g(x_1, x_2) \leq d_g(x_1, x) + d_g(x, x_2) < \eta.$$

This contradiction proves the claim.

As a consequence of self-contractedness, the sets  $\mathcal{D}^-(\eta)$  (subset of  $I$ ) and  $\gamma(\mathcal{D}^-(\eta))$  (subset of  $\mathcal{K}$ ) have the same cardinality, for every  $\eta > 0$ . The claim yields that this cardinality is bounded by  $N(\eta)$ . Compactness of  $\mathcal{K}$  guarantees that this latter is finite.  $\square$

**Remark 3.3** (Cardinality of  $\mathcal{D}^+(\eta)$ ). Analogous results hold for right discontinuities. Let  $\eta > 0$ , and let us consider the set of points of  $I$  where  $\gamma$  has a large right discontinuity:

$$\text{(right-}\eta\text{-threshold)} \quad \mathcal{D}^+(\eta) := \{\tau \in I : d_g(\gamma(\tau), \gamma(\tau^+)) \geq \eta\}. \quad (3.3)$$

Then the cardinality of the set  $\mathcal{D}^+(\eta)$  is bounded by  $N(\eta)$ .

**3.2. Describing backward secants.** Let us fix  $\tau \in (0, T_\infty)$  and let us define the set of all possible limits of *backward secants* at  $x = \gamma(\tau)$  as follows:

$$\text{sec}^-(\tau) := \left\{ p \in U_x \mathcal{M} : p = \lim_{s_k \rightarrow \tau, s_k < \tau} u_x(\gamma(s_k)) \right\}.$$

Notice that  $\text{sec}^-(\tau) \neq \emptyset$  for every  $\tau > 0$  (c.f. compactness of the unit sphere).

For every  $\tau \in I$ , we define the set  $\Gamma(\tau)$  (tail of  $\gamma$  at  $x = \gamma(\tau)$ ) by

$$\Gamma(\tau) := \{\gamma(t) : t \geq \tau\}.$$

and, given an open neighborhood  $\mathcal{U}$  of  $x = \gamma(\tau)$ , we define the  $\mathcal{U}$ -truncated tail of  $\gamma$  at  $x$  by

$$\Gamma_{\mathcal{U}}(\tau) := \Gamma(\tau) \cap \mathcal{U}. \quad (3.4)$$

The cone in  $T_x \mathcal{M}$  generated by  $\{u_x(z) : z \in \Gamma_{\mathcal{U}}(\tau)\}$  will be denoted  $C_{x, \mathcal{U}}$ . The next result asserts that every backward secant at a point  $x = \gamma(\tau)$  where the curve is left continuous, is normal to  $C_{x, \mathcal{U}}$ .

**Lemma 3.4** (Backward secants). *Let  $\mathcal{U}$  be an open neighborhood of  $x = \gamma(\tau)$  with  $\text{diam } \mathcal{U} \leq \rho$ . (I) If  $\gamma$  is left continuous at  $\tau$ , then*

$$\text{sec}^-(\tau) \subset N_{\exp_x^{-1}(\Gamma_{\mathcal{U}}(\tau))}(x) \quad (3.5)$$

that is,

$$\langle p, u_x(z) \rangle_x \leq 0, \quad \text{for all } p \in \text{sec}^-(\tau) \text{ and } z \in \Gamma_{\mathcal{U}}(\tau) \setminus \{x\}.$$

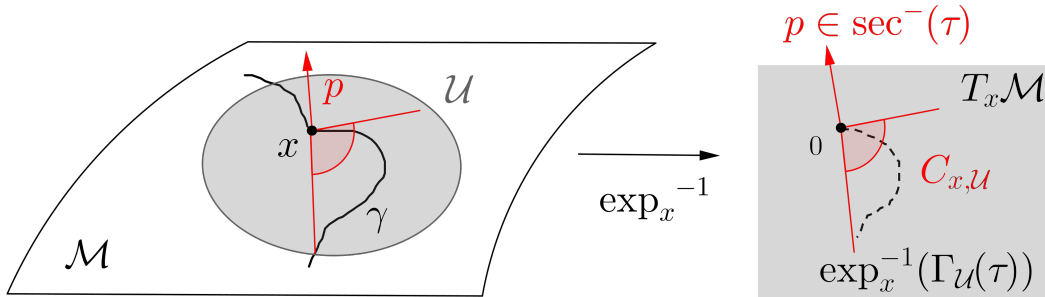


FIGURE 2.  $\text{sec}^-(\tau) \subseteq N_{\exp_x^{-1}(\Gamma_{\mathcal{U}}(\tau))}(x)$

(II) If  $x \neq \gamma(\tau^-)$  and  $\gamma(\tau^-) \in B_g(x, 2\rho)$  then

$$\text{sec}^-(\tau) = \{u_x(\gamma(\tau^-))\}.$$

**Proof.** (I) Let  $p \in \sec^-(\tau)$ . Then for some  $s_k \nearrow \tau$  we have

$$p := \lim_{k \rightarrow \infty} \frac{\exp_x^{-1}(\gamma(s_k))}{|\exp_x^{-1}(\gamma(s_k))|_x} \quad (\text{in } T_x\mathcal{M}).$$

Clearly  $\mathcal{U} \subset B_g(x, 2\rho)$ . We may also assume that  $\Gamma_{\mathcal{U}}(\tau) \setminus \{x\} \neq \emptyset$  (else the conclusion follows trivially) and  $\{\gamma(s_k)\}_k \subset \mathcal{U}$ . Pick any  $z \in \Gamma_{\mathcal{U}}(\tau) \setminus \{x\}$ . Applying the cosine law (2.5) we have

$$|d_g(\gamma(s_k), z)^2 - d_g(x, z)^2 - d_g(x, \gamma(s_k))^2 + 2\langle \exp_x^{-1}(\gamma(s_k)), \exp_x^{-1}(z) \rangle_x| \leq K d(x, \gamma(s_k))^2 d(x, z)^2.$$

On the other hand, since  $\gamma$  is self-contracted, we have

$$d_g(\gamma(s_k), z) \geq d_g(x, z),$$

thus

$$-d_g(x, \gamma(s_k))^2 + 2 d_g(x, z) \langle \exp_x^{-1}(\gamma(s_k)), u_x(z) \rangle_x \leq K d_g(x, \gamma(s_k))^2 d_g(x, z)^2.$$

Dividing by  $|\exp_x^{-1}(\gamma(s_k))|_x = d_g(x, \gamma(s_k))$  and passing to the limit as  $k \rightarrow \infty$  we conclude easily.

(II) It is straightforward since  $x \neq \gamma(\tau^-)$  and  $\gamma(\tau^-)$  is the limit of  $\gamma(s)$  as  $s \nearrow \tau$ .  $\square$

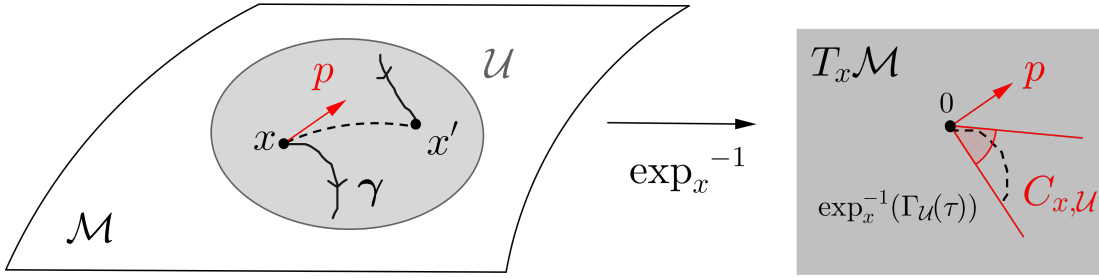


FIGURE 3.  $\sec^-(\tau) := \{u_x(\gamma(\tau^-))\} \not\subseteq N_{\exp_x^{-1}(\Gamma_{\mathcal{U}}(\tau))}(x)$

**Remark 3.5.** Notice that for  $\tau \in \mathcal{D}^-$ , the backward secant is unique (c.f. Lemma 3.4 (II)), but (3.5) may fail. An illustration is given in FIG. 3.

**3.3. Aperture of the truncated tail.** Given any subset  $C$  of the unit sphere of  $\mathbb{R}^n$ , its *aperture*  $A(C)$  is defined as follows:

$$A(C) := \inf \{ \langle u_1, u_2 \rangle : u_1, u_2 \in C \}. \quad (3.6)$$

For every  $y \in \mathcal{M}$  and  $\Gamma \subset B_g(x, 2\rho)$ , we define (the *aperture* of  $\Gamma \subset \mathcal{M}$  at  $y \in \mathcal{M}$ ):

$$A_y(\Gamma) := \inf \left\{ \langle u_y(z_1), u_y(z_2) \rangle_y : z_1, z_2 \in \Gamma \setminus \{y\} \right\}. \quad (3.7)$$

Roughly speaking, the aperture of a subset  $\Gamma$  of a manifold  $\mathcal{M}$  (with respect to a point  $y \in \mathcal{M}$ ) measures the size of the cone generated by the unit tangents  $u \in T_y\mathcal{M}$  at  $y$  corresponding to all points  $z \in \Gamma \setminus \{y\}$  via the mapping  $\exp_y^{-1}$ .

The aperture will play a major role in the sequel. The set  $\Gamma$  will be taken to be the (truncated) tail  $\Gamma_{\mathcal{U}}(\tau)$  of the self-contracted curve  $\gamma$  (see 3.4), and the point  $y \in \mathcal{M}$  at which the aperture is taken will be either:

- (i) the point  $x = \gamma(\tau)$  if the curve  $\gamma$  is continuous at  $\tau$ ; or



- (ii) a point  $\bar{x}$  lying in the minimal geodesic joining  $x = \gamma(\tau)$  to  $x' = \gamma(\tau^-)$ , if  $\gamma$  is left discontinuous at  $\tau$ .

### 3.3.1. Left-continuous case.

**Proposition 3.6** (Aperture of  $\Gamma_{\mathcal{U}}(\tau)$  at  $x$ ). *Let  $\mathcal{U}$  be any nonempty open subset of  $\mathcal{M}$  with  $\text{diam}\mathcal{U} \leq \rho$ . Then for every  $\tau \in (0, T_\infty)$  with  $x = \gamma(\tau) \in \mathcal{U}$  the following property holds:*

$$A_x(\Gamma_{\mathcal{U}}(\tau)) \geq -\alpha. \quad (3.8)$$

**Proof.** Set  $x := \gamma(\tau)$  and for  $i \in \{1, 2\}$  let  $z_i = \gamma(t_i) \in \Gamma_{\mathcal{U}}(\tau) \setminus \{x\}$  with  $\tau < t_1 \leq t_2$ . Applying the law of cosines (2.5) we deduce

$$d_g(z_1, z_2)^2 - d_g(x, z_1)^2 - d_g(x, z_2)^2 + 2\langle \exp_x^{-1}(z_1), \exp_x^{-1}(z_2) \rangle_x \geq -Kd(x, z_1)^2 d(x, z_2)^2.$$

Self-contractedness of  $\gamma$  yields that  $d_g(x, z_2) \geq d_g(z_1, z_2)$ , thus

$$2\langle \exp_x^{-1}(z_1), \exp_x^{-1}(z_2) \rangle_x \geq -Kd(x, z_1)^2 d(x, z_2)^2.$$

Dividing by  $|\exp_x^{-1}(z_1)|_x |\exp_x^{-1}(z_2)|_x = d_g(x, z_1)d_g(x, z_2)$ , and then using (2.6) we obtain

$$\langle u_x(z_1), u_x(z_2) \rangle_x \geq -\frac{K\rho^2}{2} \geq -\alpha/8 \geq -\alpha.$$

□

**Remark 3.7.** Roughly speaking, the above result asserts that the cone generated by the  $\mathcal{U}$ -truncated tail  $\Gamma_{\mathcal{U}}(\tau)$  at  $T_x\mathcal{M}$  has angle almost equal (a bit more than)  $\pi/2$ , for any open neighborhood  $\mathcal{U}$  of  $x$  of sufficiently small diameter. This is the Riemannian analogue of [10, Section 3, Formula (2)] (see also [4, FIG. 1]).

3.3.2. *Left-discontinuous case.* Let  $\tau \in \mathcal{D}^-$  (that is,  $\gamma$  is left-discontinuous at  $x = \gamma(\tau)$ ). In this case, for reasons that will become transparent in Section 3.4 (see also Remark 3.5), we need to consider the aperture of the truncated tail  $\Gamma_{\mathcal{U}}(\tau)$  with respect to a different point  $\bar{x}$  (other than  $x = \gamma(\tau)$ ). This point will be taken on the minimal geodesic joining  $x$  to  $x'$  and relatively close to  $x' := \gamma(\tau^-)$ . To define this geodesic, notice that  $p := u_x(x')$  is the unique left secant of  $\gamma$  at  $\tau$  (c.f. Lemma 3.4 (II)), that is, the initial velocity of the unit speed geodesic  $\theta : [0, d_g(x, x')] \rightarrow \mathcal{M}$  joining  $x$  to  $x'$ . We fix

$$\beta = \alpha/8 \quad (3.9)$$

and we denote

$$\bar{x} = \theta((1 - \beta)d_g(x, x')) \quad \text{and} \quad \bar{p} = \dot{\theta}((1 - \beta)d_g(x, x')) = u_{\bar{x}}(x'). \quad (3.10)$$

Notice that the value of  $\beta$  which determines the exact location of the point  $\bar{x}$  is the same for all  $\tau \in \mathcal{D}^- \setminus \mathcal{D}^-(\eta)$ .

**Proposition 3.8** (Aperture of  $\Gamma_{\mathcal{U}}(\tau)$  at  $\bar{x}$ ). *Let  $\tau \in \mathcal{D}^-$  and set  $x = \gamma(\tau)$ ,  $x' = \gamma(\tau^-)$  and  $\bar{x}$  defined by (3.10). Then for every open subset  $\mathcal{U}$  of  $\mathcal{M}$  with  $\text{diam}\mathcal{U} \leq \rho$  and  $\{x, \bar{x}, x'\} \subset \mathcal{U}$  we have*

$$A_{\bar{x}}(\Gamma_{\mathcal{U}}(\tau)) \geq -\alpha.$$

The proof of the above proof will not be an easy task though. Indeed, since  $\bar{x}$  is not a point of  $\gamma$ , the previous argument (c.f. proof of Lemma 3.6), based on self-contractedness, is no longer valid. Our new task will require several technical estimations (see forthcoming Lemma 3.10 and Lemma 3.11), as well as estimating the aperture of  $\Gamma_{\mathcal{U}}(\tau)$  at the point  $x'$  (which might not be a point of the curve, but belongs to its closure).

**Lemma 3.9** (Aperture of  $\Gamma_{\mathcal{U}}(\tau)$  at  $x'$ ). *Let  $\mathcal{U}$  be an open subset of  $\mathcal{M}$  with  $\text{diam}\mathcal{U} \leq \rho$  and let  $\tau \in \mathcal{D}^-$  be such that both  $x = \gamma(\tau)$  and  $x' := \gamma(\tau^-)$  are in  $\mathcal{U}$ . Then*

$$A_{x'}(\Gamma_{\mathcal{U}}(\tau)) \geq -\alpha/8. \quad (3.11)$$

**Proof.** By Lemma 3.6 (and more precisely, using the estimate of the last line of its proof), the estimation  $A_{\gamma(s)}(\Gamma_{\mathcal{U}}(\tau)) \geq -\alpha/8$  holds true for all  $s \in (0, \tau)$  point of continuity of  $\gamma$  sufficiently close to  $\tau$  so that  $\mathcal{U} \subset B_g(\gamma(s), \rho)$ . Since  $x' := \lim_{s \nearrow \tau} \gamma(s)$  is a limit of points of continuity of  $\gamma$ , We conclude easily by a standard continuity argument.  $\square$

We now fix notations that will be used in Lemma 3.13, Lemma 3.11 and Proposition 3.12. Let  $\tau \in \mathcal{D}^-$  and set  $x = \gamma(\tau)$ ,  $x' = \gamma(\tau^-)$  and  $\bar{x} = \theta((1 - \beta)d_g(x, x'))$  satisfying (3.9) and (3.10). We also fix an open  $\mathcal{U}$  of  $\mathcal{M}$  with  $\text{diam}\mathcal{U} < \rho$  and  $\{x, \bar{x}, x'\} \subset \mathcal{U}$ . If  $z \in \Gamma_{\mathcal{U}}(\tau)$ , we denote:

$$\sigma := d_g(x, x'), \quad \bar{d} = d_g(\bar{x}, z) \quad \text{and} \quad d' = d_g(x', z).$$

**Lemma 3.10** (Technical estimations - I). *For every  $z \in \Gamma_{\mathcal{U}}(\tau)$  one has:*

$$\frac{\sigma}{\bar{d}} \leq \frac{2}{1 - 2\beta} \quad (3.12)$$

and

$$\frac{d'}{\bar{d}} \leq \frac{1}{1 - 2\beta}. \quad (3.13)$$

**Proof.** Since  $\gamma$  is self-contracted, we have  $d_g(x, z) \leq d_g(x', z)$ . Therefore

$$d_g(x, x') \leq d_g(x, z) + d_g(x', z) \leq 2d_g(x', z).$$

It follows by (3.10) that  $d_g(\bar{x}, x') = \beta d_g(x, x') = \beta\sigma$ . Thus, we deduce

$$\frac{\sigma}{2} = \frac{1}{2}d_g(x, x') \leq d_g(x', z) \leq d_g(\bar{x}, z) + d_g(\bar{x}, x') = \bar{d} + \beta\sigma.$$

which yields (3.12). We now deduce from (3.12) that

$$d' = d_g(x', z) \leq d_g(x', \bar{x}) + d_g(\bar{x}, z) \leq \beta\sigma + \bar{d} \leq \left(\frac{1}{1 - 2\beta}\right) \bar{d}.$$

This proves (3.13).  $\square$

**Lemma 3.11** (Technical estimations - II). *For every  $z \in \Gamma_{\mathcal{U}}(\tau)$  we have*

$$\bar{d}^2 - d'^2 \geq -2(\beta\sigma)^2 - 2\beta\sigma\bar{d}, \quad (3.14)$$

and

$$\bar{d}^2 - d'^2 \leq 2(\beta\sigma)^2 + \beta\sigma d' \alpha/4. \quad (3.15)$$

**Proof.** Let  $z \in \Gamma_{\mathcal{U}}(\tau)$ . By the law of cosines (Lemma 2.4)

$$|d_g(x', z)^2 - d_g(\bar{x}, x')^2 - d_g(\bar{x}, z)^2 + 2\langle \exp_{\bar{x}}^{-1}(x'), \exp_{\bar{x}}^{-1}(z) \rangle_{\bar{x}}| \leq K d_g(\bar{x}, x')^2 d_g(\bar{x}, z)^2.$$

Therefore, recalling that  $d_g(\bar{x}, x') = \beta\sigma$ ,

$$\bar{d}^2 - d'^2 \geq -(\beta\sigma)^2 [1 + K d_g(\bar{x}, z)^2] + 2\langle \exp_{\bar{x}}^{-1}(x'), \exp_{\bar{x}}^{-1}(z) \rangle_{\bar{x}}$$

Since  $\bar{x}, z \in \mathcal{U}$ , we have  $d_g(\bar{x}, z) \leq \rho$ , so using (2.6), we have  $K d_g(\bar{x}, z)^2 \leq 1$ . On the other hand, by the Cauchy-Schwartz inequality, we have also  $\langle \exp_{\bar{x}}^{-1}(x'), \exp_{\bar{x}}^{-1}(z) \rangle_{\bar{x}} \geq -d_g(\bar{x}, x') d_g(\bar{x}, z)$ . Thus (3.14) holds.

To establish (3.15), we use again the law of cosines :

$$|d_g(\bar{x}, z)^2 - d_g(\bar{x}, x')^2 - d_g(x', z)^2 + 2\langle \exp_{x'}^{-1}(\bar{x}), \exp_{x'}^{-1}(z) \rangle_{x'}| \leq K d_g(\bar{x}, x')^2 d_g(x', z)^2. \quad (3.16)$$

Since  $x \in \Gamma_{\mathcal{U}}(\tau)$  and  $x \neq x'$  we deduce by Lemma 3.9 that

$$\langle u_{x'}(\bar{x}), u_{x'}(z) \rangle_{x'} = \langle u_{x'}(x), u_{x'}(z) \rangle_{x'} \geq -\alpha/8,$$

hence

$$\langle \exp_{x'}^{-1}(\bar{x}), \exp_{x'}^{-1}(z) \rangle_{x'} = d_g(\bar{x}, x') d_g(x', z) \langle u_{x'}(x), u_{x'}(z) \rangle_{x'} \geq -\beta \sigma d' \alpha / 8.$$

Combining this inequality with (3.16) and recalling that  $d_g(\bar{x}, x') = \beta \sigma$ , we get

$$\bar{d}^2 - d'^2 \leq (1 + K d_g(x', z)^2) (\beta \sigma)^2 + \beta \sigma d' \alpha / 4.$$

Since  $d_g(x', z) \leq \rho$  and  $K \rho^2 \leq 1$  (c.f. (2.6)) we conclude easily.  $\square$

**Proof of Proposition 3.8.** Since  $x' \notin \Gamma_{\mathcal{U}}(\tau)$  we deduce by Lemma 3.9 that for every  $z_1, z_2 \in \Gamma_{\mathcal{U}}(\tau)$ ,

$$\langle u_{x'}(z_1), u_{x'}(z_2) \rangle_{x'} \geq -\alpha/8. \quad (3.17)$$

In order to simplify notation, let us set  $\sigma := d_g(x, x')$  and

$$\begin{cases} d_i := d_g(x, z_i) \\ \bar{d}_i := d_g(\bar{x}, z_i) \\ d'_i := d_g(x', z_i) \end{cases} \quad \text{for } i \in \{1, 2\}.$$

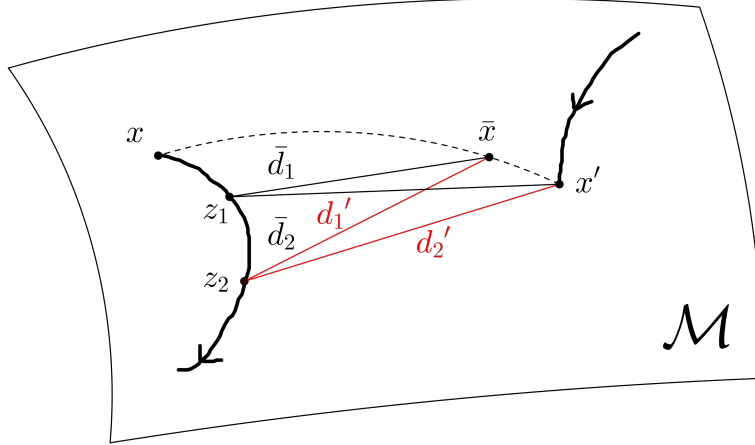


FIGURE 4

Applying the law of cosines and setting

$$e := d_g(z_1, z_2)$$

we obtain

$$|e^2 - d_1'^2 - d_2'^2 + 2 d_1' d_2' \langle u_{x'}(z_1), u_{x'}(z_2) \rangle_{x'}| \leq K d_1'^2 d_2'^2. \quad (3.18)$$

and

$$|e^2 - \bar{d}_1^2 - \bar{d}_2^2 + 2 \bar{d}_1 \bar{d}_2 \langle u_{\bar{x}}(z_1), u_{\bar{x}}(z_2) \rangle_{\bar{x}}| \leq K \bar{d}_1^2 \bar{d}_2^2. \quad (3.19)$$

Combining (3.17), (3.18) and (3.19) we deduce

$$2 \bar{d}_1 \bar{d}_2 \langle u_{\bar{x}}(z_1), u_{\bar{x}}(z_2) \rangle_{\bar{x}} \geq -d_1' d_2' \alpha / 4 - K (\bar{d}_1^2 \bar{d}_2^2 + d_1'^2 d_2'^2) + \bar{d}_1^2 - d_1'^2 + \bar{d}_2^2 - d_2'^2,$$

thus in particular

$$\langle u_{\bar{x}}(z_1), u_{\bar{x}}(z_2) \rangle_{\bar{x}} \geq - \left( \frac{d'_1 d'_2}{\bar{d}_1 \bar{d}_2} \right) \frac{\alpha}{8} - \frac{K}{2} \bar{d}_1 \bar{d}_2 \left( 1 + \left( \frac{d'_1 d'_2}{\bar{d}_1 \bar{d}_2} \right)^2 \right) + \frac{\bar{d}_1^2 - d'^2_1}{2 \bar{d}_1 \bar{d}_2} + \frac{\bar{d}_2^2 - d'^2_2}{2 \bar{d}_1 \bar{d}_2}. \quad (3.20)$$

To proceed, we need to bound the last two terms of (3.20). Applying Lemma 3.11 we obtain

$$\bar{d}_i^2 - d'^2_i \geq -2(\beta\sigma)^2 - 2(\beta\sigma)\bar{d}_i, \quad \text{for } i \in \{1, 2\},$$

thus, dividing by  $2\bar{d}_1\bar{d}_2$  we deduce in view of (3.12) and (2.6) that

$$\frac{\bar{d}_i^2 - d'^2_i}{2\bar{d}_1\bar{d}_2} \geq -\frac{4\beta^2}{(1-2\beta)^2} - \frac{2\beta}{1-2\beta} = -\frac{2\beta}{(1-2\beta)^2}.$$

Using the above estimation, together with (3.12) and (3.13), we deduce from (3.20) that

$$\begin{aligned} \langle u_{\bar{x}}(z_1), u_{\bar{x}}(z_2) \rangle_{\bar{x}} &\geq -\frac{1}{(1-2\beta)^2} \frac{\alpha}{8} - \frac{K}{2} \rho^2 \left( 1 + \frac{1}{(1-2\beta)^4} \right) - \frac{4\beta}{(1-2\beta)^2} \\ &\geq -\frac{\alpha}{8} \left( 1 + \frac{5}{(1-2\beta)^2} + \frac{1}{(1-2\beta)^4} \right). \end{aligned}$$

Since  $2\beta = \frac{\alpha}{4} \leq \frac{1}{512}$ , we obtain  $\langle u_{\bar{x}}(z_1), u_{\bar{x}}(z_2) \rangle_{\bar{x}} \geq -\alpha$ .  $\square$

The following result is the analogue of Lemma 3.4 (I) for the left-discontinuous case. Roughly speaking, the result (almost) remedies the failure illustrated in Remark 3.5 by moving the point  $x = \gamma(\tau)$  (where  $\gamma$  is left-discontinuous) to  $\bar{x} := \theta((1-\beta)d_g(x, x'))$  (see (3.10)) and making a parallel transportation of the secant  $p := u_x(x')$  at  $x$  to  $\bar{p} = u_{\bar{x}}(x') \in T_{\bar{x}}\mathcal{M}$  along the geodesic  $\theta$  joining  $x$  to  $\bar{x}$ .

**Proposition 3.12** (Transported secant). *Under the above notation and under the assumptions given before Lemma 3.10,*

$$\langle \bar{p}, u_{\bar{x}}(z) \rangle_{\bar{x}} := \langle u_{\bar{x}}(x'), u_{\bar{x}}(z) \rangle_{\bar{x}} < \alpha, \quad \text{for all } z \in \Gamma_{\mathcal{U}}(\tau).$$

**Proof.** Let  $z \in \Gamma_{\mathcal{U}}(\tau)$ , and recall that  $\sigma := d_g(x, x')$ ,  $\bar{d} = d_g(\bar{x}, z)$  and  $d' = d_g(x', z)$ . We again apply the law of cosines to get

$$d'^2 - (\beta\sigma)^2 - \bar{d}^2 + 2\beta\sigma\bar{d} \langle u_{\bar{x}}(x'), u_{\bar{x}}(z) \rangle_{\bar{x}} \leq K(\beta\sigma)^2 \bar{d}^2. \quad (3.21)$$

Notice that (3.15) yields

$$\frac{\bar{d}^2 - d'^2}{2\beta\sigma\bar{d}} \leq \frac{\beta\sigma}{\bar{d}} + \left( \frac{d'}{\bar{d}} \right) \frac{\alpha}{8}. \quad (3.22)$$

Combining (3.21) with (3.22) and using (3.12) and (3.13) we deduce (recall that  $\beta\sigma \leq \rho$  and  $\bar{d} \leq \rho$ ) we get

$$\langle u_{\bar{x}}(x'), u_{\bar{x}}(z) \rangle_{\bar{x}} \leq \frac{K}{2} \rho^2 + \frac{3\beta\sigma}{2\bar{d}} + \left( \frac{d'}{\bar{d}} \right) \frac{\alpha}{8} \leq \frac{\alpha}{8} + \frac{3\beta}{1-2\beta} + \left( \frac{1}{1-2\beta} \right) \frac{\alpha}{8}.$$

So  $\langle u_{\bar{x}}(x'), u_{\bar{x}}(z) \rangle_{\bar{x}} < 4\beta + \frac{\alpha}{2} \leq \alpha$ .  $\square$

**3.4. Estimations involving “almost secants”.** We now show that at each point of left-continuity as well as at each point of left discontinuity up to a certain discontinuity jump, a self-contracted curve grows backwards (with a uniform quantitative estimate) in some direction. We call this direction  $p^a$  an almost secant (because it is a modification of a secant  $p$ ).

**Theorem 3.13** (Measuring growth using “almost secants”). *Let  $\gamma : [0, T_\infty) \rightarrow \mathcal{M}$  be a self-contracted curve and let us fix  $x = \gamma(\tau)$  with  $\tau \in (0, T_\infty)$ .*

- (i) *If  $\gamma$  is continuous at  $\tau$ , for every  $p \in \text{sec}^-(\tau)$ , there exists  $p^a \in U_x \mathcal{M}$  such that for every open subset  $\mathcal{U}$  of  $\mathcal{M}$  with  $x \in \mathcal{U}$  and  $\text{diam} \mathcal{U} \leq \rho$ , and every  $z \in \Gamma_{\mathcal{U}}(\tau)$ ,*

$$\langle p^a, u_x(z) \rangle_x \leq -3\alpha \quad \text{and} \quad \langle p^a, p \rangle_x \geq 4\alpha$$

- (ii) *If  $\tau \in \mathcal{D}^- \setminus \mathcal{D}^-(\eta)$ , if we denote  $\bar{p} = u_{\bar{x}}(x')$  the transported secant at  $\bar{x}$ , there exists  $p^a \in U_{\bar{x}} \mathcal{M}$  such that for every open subset  $\mathcal{U}$  of  $\mathcal{M}$  with  $\{x, \bar{x}, x'\} \subset \mathcal{U}$  and  $\text{diam} \mathcal{U} \leq \rho$ , and every  $z \in \Gamma_{\mathcal{U}}(\tau)$ ,*

$$\langle p^a, u_{\bar{x}}(z) \rangle_{\bar{x}} \leq -3\alpha \quad \text{and} \quad \langle p^a, \bar{p} \rangle_{\bar{x}} \geq 4\alpha$$

We need a separation lemma for subsets of the unit sphere of  $\mathbb{R}^n$  with a controlled aperture.

**Lemma 3.14** (Strong separation lemma). *Let  $C$  be a nonempty subset of the unit sphere of  $\mathbb{R}^n$  satisfying*

$$A(C) \geq -\delta, \tag{3.23}$$

where

$$\delta = \frac{1}{2(n+1)}. \tag{3.24}$$

Then

$$\overline{\text{conv}}(C) \cap B(0, \delta) = \emptyset. \tag{3.25}$$

**Proof of Lemma 3.14.** Let us assume, towards a contradiction, that for some  $u \in \overline{\text{conv}}(C)$  we have  $\|u\| < \delta$ . By Caratheodory’s lemma there exist  $\lambda_0, \dots, \lambda_n \in [0, 1]$  with  $\sum_{i=0}^n \lambda_i = 1$  and unit vectors  $u_0, \dots, u_n \in C$  such that

$$\left\| \sum_{i=0}^n \lambda_i u_i \right\| < \delta.$$

Let  $i_0 \in \{0, \dots, n\}$  be such that  $\lambda_{i_0} \geq \lambda_i$  for any  $i \in \{0, \dots, n\}$ . Then  $\lambda_{i_0} \geq 1/(n+1)$  and by the Cauchy-Schwarz inequality

$$\begin{aligned} \delta &> \langle u_{i_0}, \sum_{i=0}^n \lambda_i u_i \rangle = \sum_{i=0}^n \lambda_i \langle u_{i_0}, u_i \rangle = \lambda_{i_0} + \sum_{i \neq i_0} \lambda_i \langle u_{i_0}, u_i \rangle \\ &> \frac{1}{n+1} - \delta \left( \sum_{i \neq i_0} \lambda_i \right) > \frac{1}{n+1} - \delta = \delta, \end{aligned}$$

a clear contradiction. Thus the assertion holds true.  $\square$

**Proof of Theorem 3.13.** Both assertions follow by the same arguments and estimations. In order to present a common proof let us proceed to the following identification:

- If  $x = \gamma(\tau) = \gamma(\tau^-)$ , we identify the tangent space  $T_x \mathcal{M}$  equipped with the scalar product  $\langle \cdot, \cdot \rangle_x$  with the Euclidean space  $\mathbb{R}^n$ .

- If  $x = \gamma(\tau) \neq \gamma(\tau^-)$ , we identify the tangent space  $T_{\bar{x}}\mathcal{M}$  equipped with the scalar product  $\langle \cdot, \cdot \rangle_{\bar{x}}$  with the Euclidean space  $\mathbb{R}^n$ .

In the sequel, we shall denote (in both cases) this scalar product by  $\langle \cdot, \cdot \rangle$ . We further set

$$C = \{u_x(z) : z \in \Gamma_{\mathcal{U}}(\tau)\} \quad (\text{respectively } C = \{u_{\bar{x}}(z) : z \in \Gamma_{\mathcal{U}}(\tau)\}).$$

Since  $\alpha = \delta^2/8 \leq \delta$ , Proposition 3.6 and Proposition 3.8 imply that  $A(C) \geq -\delta$ . Applying Lemma 3.14, we obtain that the projection of 0 to  $\overline{\text{conv}}(C)$ , denoted by  $c \in T_x\mathcal{M}$ , satisfies for every  $u \in C$

$$\|c\| \geq \delta \quad \text{and} \quad \langle -c, u - c \rangle \leq 0.$$

It follows

$$\langle -c, u \rangle \leq -\|c\|^2 \leq -\delta^2 = -8\alpha. \quad (3.26)$$

(i) Let  $\tau \in (0, T_{\infty}) \setminus \mathcal{D}^-$  and fix any backward secant  $p \in \text{sec}^-(\tau) \in T_x\mathcal{M} \equiv \mathbb{R}^n$  and set

$$p^a := \frac{p - c}{\|p - c\|}.$$

By Lemma 3.4 (I) we get  $\langle p, u \rangle \leq 0$ , for all  $u \in C$ . Then for every  $u \in C$  (unit vector) in view of (3.26) we deduce

$$\langle p^a, u \rangle = \frac{\langle p, u \rangle + \langle -c, u \rangle}{\|p - c\|} \leq \frac{0 - \|c\|^2}{\|p - c\|} \leq \frac{-8\alpha}{\|p - c\|} \leq -3\alpha,$$

where the fact that  $\|p - c\| \leq 2$  is used. Finally, if  $u \in U_x\mathcal{M}$  and  $\|p - u\| < \alpha$ ,

$$\langle p^a, p \rangle \geq \frac{\|p\|^2 + \langle -c, p \rangle}{\|p - c\|} \geq \frac{1 + 0}{2} \geq 4\alpha.$$

(ii) Let  $\tau \in \mathcal{D}^-$  and consider the transported secant  $\bar{p} = u_{\bar{x}}(x') \in T_x\mathcal{M} \equiv \mathbb{R}^n$  at  $\bar{x}$ . In an analogous manner to the above, we set

$$p^a := \frac{\bar{p} - c}{\|\bar{p} - c\|}.$$

By Proposition 3.12 we get

$$\langle \bar{p}, u \rangle \leq \alpha, \quad \text{for all } u \in C. \quad (3.27)$$

Since  $c \in C$  we deduce

$$\|\bar{p} - c\|^2 = \|\bar{p}\|^2 + \|c\|^2 - \langle \bar{p}, c \rangle \geq 1 + \delta^2 - \alpha \geq 1.$$

In particular

$$1 \leq \|\bar{p} - c\| \leq 2.$$

For every  $u \in C$  (unit vector) in view of (3.26) and (3.27) we deduce

$$\langle p^a, u \rangle \leq \frac{\langle \bar{p}, u \rangle + \langle -c, u \rangle}{\|\bar{p} - c\|} \leq \frac{\alpha - 8\alpha}{\|\bar{p} - c\|} \leq \frac{-7\alpha}{2} \leq -3\alpha.$$

On the other hand, if  $u \in U_x\mathcal{M}$  and  $\|\bar{p} - u\| < \alpha$ , using again (3.27), we get

$$\langle p^a, \bar{p} \rangle \geq \frac{\|\bar{p}\|^2 + \langle -c, \bar{p} \rangle}{\|\bar{p} - c\|} \geq \frac{1 - \alpha}{\|\bar{p} - c\|} \geq \frac{1 - \alpha}{2} \geq 4\alpha.$$

This concludes the proof of the assertion.  $\square$

## 4. PROOF OF THE MAIN RESULT

**4.1. Width estimates via external functions.** From now on,  $\eta$  is given by Lemma 2.6,  $\mathcal{F}$  is a fixed finite  $\eta$ -net of  $UK$ , and for each  $\xi = q_y \in \mathcal{F}$ ,  $\mathcal{U}_\xi := B_g(y, 2\eta)$ . We recall that a finite subset  $\mathcal{F}$  of  $UK$  is an  $\eta$ -net if  $\mathcal{F}$  has a nonempty intersection with any ball (for the distance  $D_g$ ) of radius  $\eta$  centered at a point of  $UK$ . The existence of the finite  $\eta$ -net  $\mathcal{F}$  follows from the compactness of  $UK$ .

If  $\gamma$  is a self-contracted map defined on  $[0, +\infty)$  and if  $\tau \in (0, +\infty) \setminus \mathcal{D}^-(\eta)$ , we define an element  $\xi^a \in UK$  as follows. We denote  $p^a$  the almost secant given by Theorem 3.13, and we consider two cases:

- If  $\tau$  is a point of left-continuity of  $\gamma$ , for every backward secant  $p \in \text{sec}^-(\tau)$  at  $x = \gamma(\tau)$  we associate the almost secant  $p^a \in U_x\mathcal{K}$  and we set

$$\xi^a := p_x^a = (x, p^a). \quad (4.1)$$

Notice that different secants at  $x$  might give rise to different  $p^a \in U_x\mathcal{K}$  (therefore to different elements  $\xi_a \in UK$ ).

- If  $\tau \in \mathcal{D}^- \setminus \mathcal{D}^-(\eta)$ , then the backward secant  $p := u_x(x')$  at  $x = \gamma(\tau)$  is unique. Using the notation of (3.10), the almost secant associated to  $\bar{p}$  is  $p^a \in U_{\bar{x}}\mathcal{K}$ . We set:

$$\xi^a := p_{\bar{x}}^a = (\bar{x}, p^a). \quad (4.2)$$

The following result is crucial for our purposes. Roughly speaking it will be used to associate to each  $\xi^a$  constructed above an element  $\xi$  from the finite set  $\mathcal{F}$ . In this way, instead of controlling the growth of  $\gamma$  by the infinite set of ‘‘almost secants’’, we shall control this growth by the finite set of external functions.

**Lemma 4.1** (Controlling the local growth of  $\gamma$  by external functions). *Let  $\mathcal{F}$  be a finite  $\eta$ -net of  $UK$ , and, for each  $\xi = q_y \in \mathcal{F}$ , let us denote  $\mathcal{U}_\xi := B_g(y, 2\eta)$ . Then:*

- (I) *Let  $\tau \in (0, T_\infty) \setminus \mathcal{D}^-$  and  $p \in \text{sec}^-(\tau)$ , let  $\xi^a := p_x^a$  be defined as in (4.1), and let  $\xi \in \mathcal{F}$  be such that  $D_g(\xi^a, \xi) < \eta$ . If  $\gamma(s) \in \mathcal{U}_\xi$ ,  $|p - u_x(\gamma(s))|_x \leq \alpha$  and  $z \in \Gamma_{\mathcal{U}_\xi}(\tau)$ , then:*

$$\langle q, \exp_y^{-1}(\gamma(s)) \rangle_y \geq \langle q, \exp_y^{-1}(z) \rangle_y + 2\alpha d_g(\gamma(s), z). \quad (4.3)$$

- (II) *Let  $\tau \in \mathcal{D}^- \setminus \mathcal{D}^-(\eta)$ , let  $\xi^a := p_{\bar{x}}^a$  be defined by (4.2), and let  $\xi \in \mathcal{F}$  be such that  $D_g(\xi^a, \xi) < \eta$ . If  $\gamma(s) \in \mathcal{U}_\xi$ ,  $|\bar{p} - u_{\bar{x}}(\gamma(s))|_{\bar{x}} \leq \alpha$  and  $z \in \Gamma_{\mathcal{U}_\xi}(\tau)$ , then:*

$$\langle q, \exp_y^{-1}(\gamma(s)) \rangle_y \geq \langle q, \exp_y^{-1}(z) \rangle_y + 2\alpha d_g(\gamma(s), z). \quad (4.4)$$

**Proof.** Recall that  $\rho$  satisfies (2.6) and that  $\eta \in (0, \rho/4)$  is given by Lemma 2.6, so  $\text{diam}(\mathcal{U}_\xi) < \rho$ . We shall first consider the case  $\tau \in (0, T_\infty) \setminus \mathcal{D}^-$ . We fix  $p \in \text{sec}^-(\tau)$  and set  $\xi^a := p_x^a$ . Let  $\xi = q_y \in B_{D_g}(\xi^a, \eta)$ . We know from Theorem 3.13 (i) that for all  $z \in \Gamma_{\mathcal{U}_\xi}(\tau) \setminus \{x\}$ ,  $\langle p^a, u_x(z) \rangle_x \leq -3\alpha$  and  $\langle p^a, p \rangle_x \geq 4\alpha$ . If  $\gamma(s) \in \mathcal{U}_\xi$  and  $|p - u_x(\gamma(s))|_x \leq \alpha$ , we obtain from Lemma 2.6:

$$\begin{aligned} \langle q, \exp_y^{-1}(\gamma(s)) \rangle_y - \langle q, \exp_y^{-1}(x) \rangle_y &\geq (\langle p^a, u_x(\gamma(s)) \rangle_x - \alpha) d_g(x, \gamma(s)) \\ &\geq (\langle p^a, p \rangle_x - 2\alpha) d_g(x, \gamma(s)) \geq 2\alpha d_g(x, \gamma(s)). \end{aligned}$$

On the other hand, if  $z \in \Gamma_{\mathcal{U}_\xi}(\tau)$ , we deduce from Lemma 2.6 that

$$\langle q, \exp_y^{-1}(x) \rangle_y - \langle q, \exp_y^{-1}(z) \rangle_y \geq (-\langle p^a, u_x(z) \rangle_x - \alpha) d_g(x, z) \geq 2\alpha d_g(x, z).$$

Summing up these two inequalities, we obtain (4.3).

The case  $\tau \in \mathcal{D}^- \setminus \mathcal{D}^-(\eta)$  is treated similarly. Theorem 3.13 (ii) gives that for all  $z \in \Gamma_{\mathcal{U}_\xi}(\tau) \setminus \{x\}$ ,  $\langle p^a, u_{\bar{x}}(z) \rangle_{\bar{x}} \leq -3\alpha$  and  $\langle p^a, \bar{p} \rangle_{\bar{x}} \geq 4\alpha$ . If  $\gamma(s) \in \mathcal{U}_\xi$  and  $|\bar{p} - u_{\bar{x}}(\gamma(s))|_{\bar{x}} \leq \alpha$ , Lemma 2.6 gives:

$$\begin{aligned} \langle q, \exp_y^{-1}(\gamma(s)) \rangle_y - \langle q, \exp_y^{-1}(x) \rangle_y &\geq (\langle p^a, u_{\bar{x}}(\gamma(s)) \rangle_{\bar{x}} - \alpha) d_g(x, \gamma(s)) \\ &\geq (\langle p^a, \bar{p} \rangle_{\bar{x}} - 2\alpha) d_g(x, \gamma(s)) \geq 2\alpha d_g(x, \gamma(s)). \end{aligned}$$

On the other hand, if  $z \in \Gamma_{\mathcal{U}_\xi}(\tau)$ , Lemma 2.6 implies that

$$\langle q, \exp_y^{-1}(x) \rangle_y - \langle q, \exp_y^{-1}(z) \rangle_y \geq (-\langle p^a, u_{\bar{x}}(z) \rangle_{\bar{x}} - \alpha) d_g(x, z) \geq 2\alpha d_g(x, z).$$

Summing up these two inequalities, we obtain (4.4).  $\square$

For each  $\xi \in \mathcal{F}$ , we define the local width of  $\gamma$  at  $x = \gamma(\tau)$  with respect to  $\xi$  as follows:

$$W_\xi(\tau) := \text{diam} \{ \langle q, \exp_y^{-1}(z) \rangle_y : z \in \Gamma_{\mathcal{U}_\xi}(\tau) \}, \quad (4.5)$$

using the convention that  $\text{diam} \emptyset = 0$ . We are now ready to establish our fundamental result, which states that the growth of the length of a self-contracted curve is locally controlled by the decay of one of the functions  $W_\xi$ .

**Theorem 4.2.** *Let  $\gamma : [0, T_\infty) \rightarrow \mathcal{M}$  be a self-contracted map such that its range is included in the compact  $\mathcal{K}$ , let  $\mathcal{F}$  be a finite  $\eta$ -net of  $U\mathcal{K}$ , and, for each  $\xi = q_y \in \mathcal{F}$ , let us denote  $\mathcal{U}_\xi := B_g(y, 2\eta)$ . Let  $\tau \in (0, T_\infty) \setminus (\mathcal{D}^-(\eta) \cup \mathcal{D}^+(\eta))$ . There exists  $\delta > 0$  such that, for all  $s, t$  satisfying  $\tau - \delta < s < \tau < t < \tau + \delta$ , there exists  $\xi \in \mathcal{F}$  such that:*

$$W_\xi(s) - W_\xi(t) \geq \alpha d_g(\gamma(s), \gamma(t)) \quad (4.6)$$

**Proof.** (i). Let  $\tau \in (0, T_\infty) \setminus \mathcal{D}^-$  (point of left-continuity) and set  $x = \gamma(\tau)$ . Since  $\text{sec}^-(\tau)$  is the set of accumulation points of the subset  $\{u_x(\gamma(s))\}$  of  $U_x\mathcal{M}$  as  $s \nearrow \tau$ , and since  $U_x\mathcal{M}$  is compact, there exists  $\delta > 0$  such that for every  $s \in (\tau - \delta, \tau)$ , there exists  $p^s \in \text{sec}^-(\tau)$  such that  $|p^s - u_x(\gamma(s))|_x < \alpha$ . Applying Lemma 4.1 (for  $x = \gamma(\tau)$  and  $p^s \in \text{sec}^-(\tau)$ ) we get that for all  $s \in (\tau - \delta, \tau)$ , there exists  $\xi \in \mathcal{F}$  such that:

$$\forall z \in \Gamma_{\mathcal{U}_\xi}(\tau) \quad \langle q, \exp_y^{-1}(\gamma(s)) \rangle_y - \langle q, \exp_y^{-1}(z) \rangle_y \geq 2\alpha d_g(\gamma(s), z). \quad (4.7)$$

(ii). Let us now assume  $\tau \in \mathcal{D}^- \setminus \mathcal{D}^-(\eta)$ , set  $x = \gamma(\tau)$ ,  $x' = \gamma(\tau^-)$  and  $\bar{x} := \theta((1 - \beta) d_g(x, x'))$ . Since  $\bar{p} := u_{\bar{x}}(x')$  and  $x' = \lim_{s \nearrow \tau} \gamma(s)$ , there exists  $\delta > 0$  such that if  $s \in (\tau - \delta, \tau)$ , then  $|\bar{p} - u_{\bar{x}}(\gamma(s))|_{\bar{x}} < \alpha$ . In this case, Lemma 4.1 yields that, there exists  $\xi \in \mathcal{F}$  such that for all  $s \in (\tau - \delta, \tau)$ ,

$$\forall z \in \Gamma_{\mathcal{U}_\xi}(\tau) \quad \langle q, \exp_y^{-1}(\gamma(s)) \rangle_y - \langle q, \exp_y^{-1}(z) \rangle_y \geq 2\alpha d_g(\gamma(s), z). \quad (4.8)$$

Let us finally assume (in both cases (i) and (ii)) that  $\tau \notin \mathcal{D}^+(\eta)$ , that is,  $d_g(\gamma(\tau), \gamma(\tau^+)) < \eta$ . Shrinking if necessary  $\delta$ , we can assume that for all  $t \in (\tau, \tau + \delta)$ , we have  $d_g(\gamma(\tau), \gamma(t)) < \eta$ . This implies  $d_g(y, \gamma(t)) \leq d_g(y, \gamma(\tau)) + d_g(\gamma(\tau), \gamma(t)) < 2\eta$  and so  $\gamma(t) \in \mathcal{U}_\xi$  and  $\Gamma_{\mathcal{U}_\xi}(t) \neq \emptyset$ . The first inequality below follows from (4.7) and (4.8) and the fact that  $\Gamma_{\mathcal{U}_\xi}(t)$  is included in  $\Gamma_{\mathcal{U}_\xi}(\tau)$  whenever  $t > \tau$ , while the second one comes from the fact that  $\gamma$  is self-contracted. For all  $s \in (\tau - \delta, \tau)$ , there exists  $\xi \in \mathcal{F}$  such that, for all  $t \in (\tau, \tau + \delta)$  and for all  $z \in \Gamma_{\mathcal{U}_\xi}(t)$ :

$$\langle q, \exp_y^{-1}(\gamma(s)) \rangle_y - \langle q, \exp_y^{-1}(z) \rangle_y \geq 2\alpha d_g(\gamma(s), z) \geq \alpha d_g(\gamma(s), \gamma(t)).$$

Hence  $W_\xi(s) \geq W_\xi(t) + \alpha d_g(\gamma(s), \gamma(t))$ .  $\square$



**4.2. Proof of finite length.** Let  $\mathcal{F} \subset UK$  be the finite  $\eta$ -net defined in the previous section. Then for any  $\xi = q_y \in \mathcal{F}$ , the function  $z \rightarrow \langle q, \exp_y^{-1}(z) \rangle_y$  is well defined on

$$\mathcal{U}_\xi := B_g(y, 2\eta) \subset B_g(y, 2\rho).$$

We recall that  $W_\xi(\tau) := \text{diam} \{ \langle q, \exp_y^{-1}(z) \rangle_y : z \in \Gamma_{\mathcal{U}_\xi}(\tau) \}$ . Notice that for  $\tau_1 \leq \tau_2$  we have  $\Gamma_{\mathcal{U}_\xi}(\tau_2) \subset \Gamma_{\mathcal{U}_\xi}(\tau_1)$ , therefore  $W_\xi(\tau_2) \leq W_\xi(\tau_1)$ . In other words, the function  $\tau \mapsto W_\xi(\tau)$  is non increasing on  $[0, T_\infty)$  for every  $\xi \in \mathcal{F}$ . Let us now consider the (decreasing) aggregate function

$$W_{\mathcal{F}}(\tau) := \sum_{\xi \in \mathcal{F}} W_\xi(\tau).$$

The following result holds.

**Proposition 4.3.** *Let  $[a, b] \subset (0, T_\infty) \setminus (\mathcal{D}^-(\eta) \cup \mathcal{D}^+(\eta))$ . Then for every partition*

$$a = t_0 < t_1 < \dots < t_m = b$$

*of  $[a, b]$ ,*

$$\sum_{j=1}^m d_g(\gamma(t_{j-1}), \gamma(t_j)) \leq \frac{1}{\alpha} (W_{\mathcal{F}}(a) - W_{\mathcal{F}}(b)). \quad (4.9)$$

**Proof.** If  $\tau \notin \mathcal{D}^-(\eta) \cup \mathcal{D}^+(\eta)$  and  $x = \gamma(\tau)$ , Theorem 4.2 tells us that there exists  $\delta_\tau > 0$  such that  $(\tau - \delta_\tau, \tau + \delta_\tau) \cap (\mathcal{D}^-(\eta) \cup \mathcal{D}^+(\eta))$  is empty and for all  $s, t \in (\tau - \delta_\tau, \tau + \delta_\tau)$  with  $s \leq \tau \leq t$ , there exists  $\xi \in \mathcal{F}$  satisfying  $W_\xi(s) \geq W_\xi(t) + \alpha d_g(\gamma(s), \gamma(t))$ . We deduce easily from the definition of  $W_{\mathcal{F}}$  that:

$$W_{\mathcal{F}}(s) - W_{\mathcal{F}}(t) \geq \alpha d_g(\gamma(s), \gamma(t)). \quad (4.10)$$

Using a standard compactness argument, for every fixed  $i \in \{1, \dots, m\}$ , there exists a subdivision  $\{s_{i,j}\}_{j=0}^{j_i}$  of  $[t_{i-1}, t_i]$  such that (4.10) is true for  $s = s_{i,j-1}$  and  $t = t_{i,j}$ . Summing up these inequalities for all  $j$  and using the triangular inequality, we obtain that (4.10) is true for  $s = t_{i-1}$  and  $t = t_i$ . Summing up these inequalities for all  $i$  we obtain (4.9).  $\square$

We are now ready to conclude the proof of Theorem 2.1.

**Proof of Theorem 2.1.** Let  $\gamma : [0, T_\infty) \rightarrow \mathcal{M}$  be a self-contracted curve. Set  $\mathcal{N} := \mathcal{D}^-(\eta) \cup \mathcal{D}^+(\eta)$  and denote by  $|\mathcal{N}|$  its cardinality. Fix  $T < T_\infty$  and denote by  $\gamma_T$  the restriction of  $\gamma$  to the compact interval  $[0, T]$ . We shall prove that  $\gamma_T$  is rectifiable and its length is bounded by  $W_{\mathcal{F}}(0) + |\mathcal{N}| \Sigma$ , where  $\Sigma$  is a strict upper bound for the maximal left or right jump of  $\gamma$ , that is,

$$\Sigma > \max \left\{ \max_{\sigma \in \widehat{\mathcal{D}}} d_g(\gamma(\sigma), \gamma(\sigma^-)), \max_{\sigma \in \mathcal{D}^+(\eta)} d_g(\gamma(\sigma), \gamma(\sigma^+)) \right\}.$$

By proposition 3.2,  $\mathcal{N}$  is finite (and the right and left limits exist at every point), so there exists  $\delta' > 0$  such that for any  $\sigma \in \mathcal{N}$  and any  $s, t \in (\sigma - \delta', \sigma + \delta')$  with  $s \leq \sigma \leq t$  it holds

$$d_g(\gamma(s), \gamma(t)) < \Sigma. \quad (4.11)$$

Notice that the compact set  $[0, T] \setminus \bigcup_{\sigma \in \mathcal{N}} (\sigma - \delta', \sigma + \delta')$  is a finite union of intervals  $[a_i, b_i]$ , for each of which Proposition 4.3 applies. We deduce easily that

$$\ell(\gamma_T) \leq \frac{1}{\alpha} W_{\mathcal{F}}(0) + |\mathcal{N}| \Sigma.$$

Since the above bound is independent of  $T$ , passing to the limit as  $T \rightarrow +\infty$  we obtain that the length of  $\gamma$  is bounded by the same constant.  $\square$

**Remark 4.4.** Proposition 3.2 tells us that  $|\mathcal{N}| \leq |\mathcal{D}^-(\eta)| + |\mathcal{D}^+(\eta)| \leq 2N(\eta)$ , where  $N(\eta)$  is the minimal number of balls of radius  $\eta/2$  that can cover  $\mathcal{K}$ . On the other hand, for every  $\xi \in \mathcal{F}$ ,  $W_\xi(0) \leq \sup\{|\exp_y^{-1}(z_1) - \exp_y^{-1}(z_2)|_y; z_1, z_2 \in \mathcal{U}_\xi\} \leq 4\eta$ , so  $W_{\mathcal{F}}(0) \leq 4\eta|\mathcal{F}|$ . Finally,  $\Sigma \leq 2\text{diam}(\mathcal{K})$ . Therefore, the above proof shows that the upper bound for the length of any self-contracted curve  $\gamma : [0, T_\infty) \rightarrow \mathcal{K}$  only depends on the dimension of the manifold and the compact set  $\mathcal{K}$ .

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